

# Lower bounds under the Exponential Time Hypothesis

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Recent Advances in Parameterized Complexity

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# Motivation

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- **Goal:** Fine-grained complexity theory.

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- For every  $q$  you can do  $(2 - \varepsilon_q)^n$  for  $q$ SAT, but  $\lim_{q \rightarrow \infty} \varepsilon_q = 0$ .

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## ETH and SETH, first attempt

**ETH:** 3SAT cannot be solved in time  $2^{o(n)}$ .

**SETH:** CNF-SAT cannot be solved in time  $\mathcal{O}(\alpha^n)$  for any  $\alpha < 2$ .

$$\delta_q = \inf\{c : \text{There is an } \mathcal{O}(2^{cn}) \text{ algorithm for } q\text{SAT}\}$$

## Exponential Time Hypothesis, ETH

$$\delta_3 > 0.$$

There is a  $c > 0$  such that 3SAT cannot be solved in  $\mathcal{O}(2^{cn})$  time.

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- ETH is widely believed, SETH is disputed.

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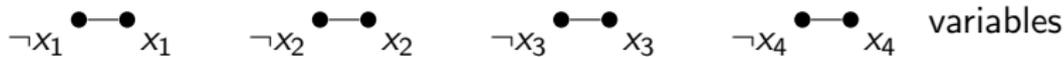
## VERTEX COVER

**I:** graph  $G$  and  $k \in \mathbb{N}$

**Q:** Is there a set  $X \subseteq V(G)$  with  $|X| \leq k$  such that every edge of  $G$  has at least one endpoint in  $X$ ?

# VERTEX COVER reduction

Let us inspect the standard reduction from 3SAT to VERTEX COVER.

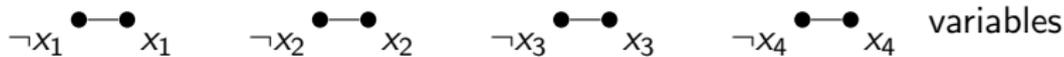
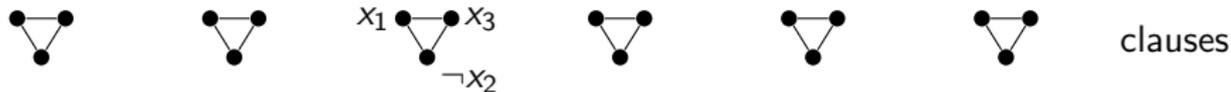


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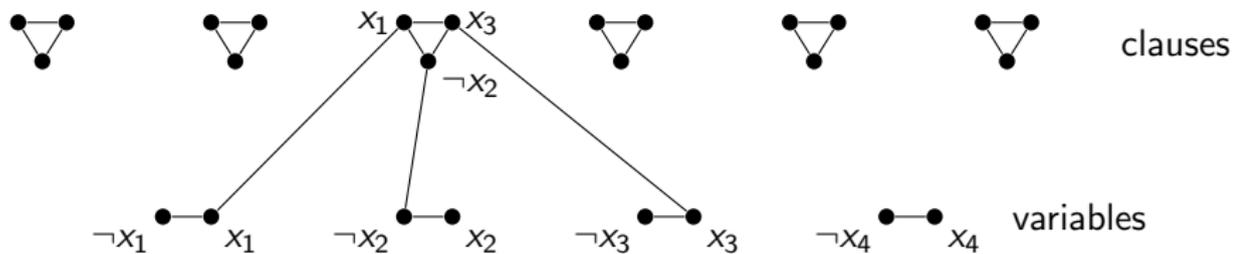


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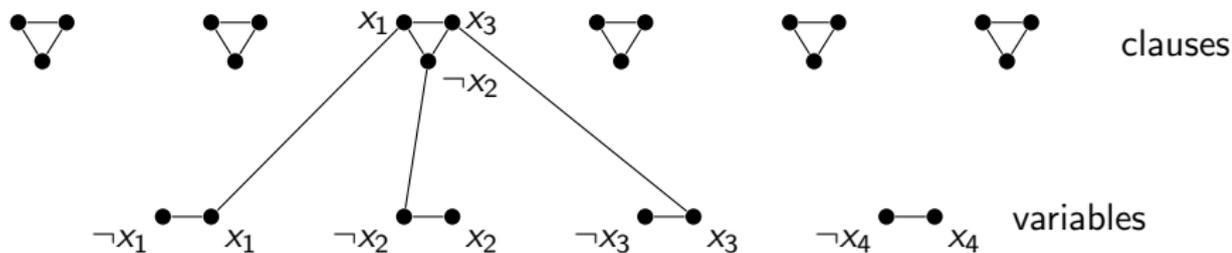


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$\varphi$  is satisfiable iff the created graph has a vertex cover of size  $n + 2m$ .

- If  $N = 2n + 3m$  is the number of vertices of the output graph, then  $N = \mathcal{O}(n + m) = \mathcal{O}(n^3)$ .

# VERTEX COVER reduction, analysis

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- **Gap:** between upper bound  $2^{\mathcal{O}(N)}$  and lower bound  $2^{o(N^{1/3})}$ .
- If we started with an instance of 3-SAT that was **sparse**, that is,  $m = \mathcal{O}(n)$ , then a  $2^{o(N)}$  lower bound would follow.

# Sparsification Lemma

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For every constant  $q$ , there is a subexponential-time algorithm which reduces the number of clauses of a  $q$ CNF formula to  $\mathcal{O}(n)$ .

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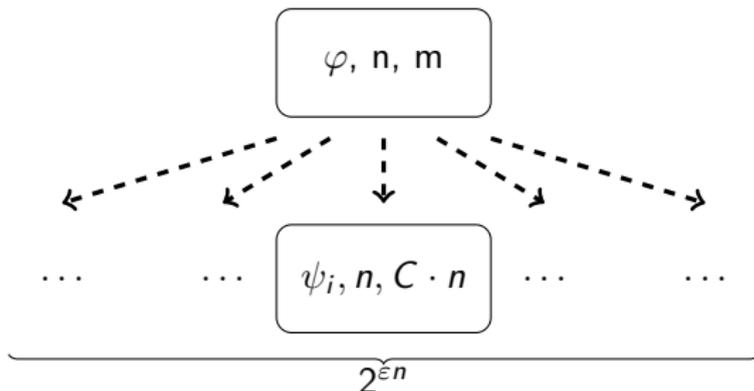
For any  $q \geq 3$  and  $\varepsilon > 0$ , there is a constant  $C = C(q, \varepsilon)$  such that any  $q$ CNF formula  $\varphi$  can be expressed as  $\varphi = \bigvee_{i=1}^t \psi_i$ , where  $t \leq 2^{\varepsilon n}$  and each  $\psi_i$  is a  $q$ CNF formula with the same set of variables and at most  $C \cdot n$  clauses. Such disjunction can be computed in time  $\mathcal{O}^*(2^{\varepsilon n})$ .

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Unless ETH fails, there is a constant  $c > 0$ , such that no algorithm solves 3SAT in time  $\mathcal{O}^*(2^{c(n+m)})$ .

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- Consider any  $d > 0$ . We want to solve 3SAT in time  $\mathcal{O}^*(2^{dn})$ .

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Unless ETH fails, there is a constant  $c > 0$ , such that no algorithm solves 3SAT in time  $\mathcal{O}^*(2^{c(n+m)})$ .

Proof by contradiction:

- Suppose that for every  $c > 0$  there is an algorithm  $\mathcal{A}_c$  solving 3SAT in time  $\mathcal{O}^*(2^{c(n+m)})$ .
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## Corollary

Under ETH, there is no  $2^{o(n+m)}$ -time algorithm for 3SAT, so also no  $2^{o(N+M)}$ -time algorithm for VERTEX COVER.

## Hardness under ETH via reductions

Suppose there is a reduction from 3SAT to a problem  $L$  that produces an instance of size  $N \leq f(n + m)$ .

Then we can exclude an algorithm for  $L$  with running time  $2^{o(f^{-1}(N))}$ .

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- Let's see tight bounds for another form of running time.

- Consider PLANAR VERTEX COVER.

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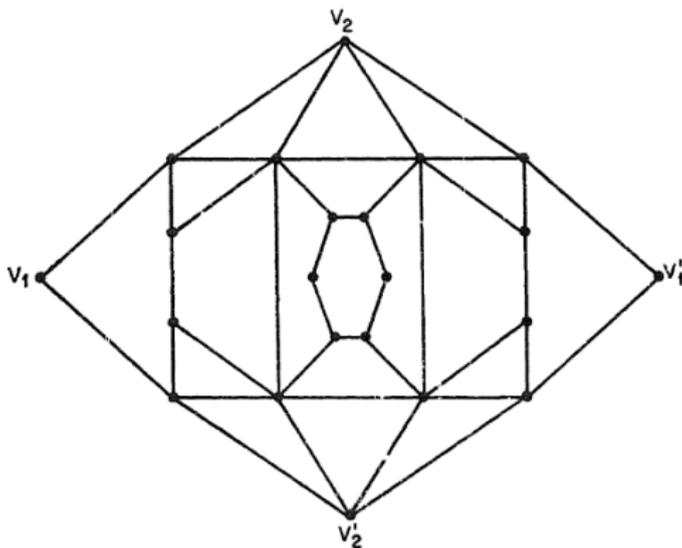


Fig. 11. Crossover  $H$  for Theorem 2.7.

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- The  $\sqrt{N}$  term in the exponent is not a coincidence!

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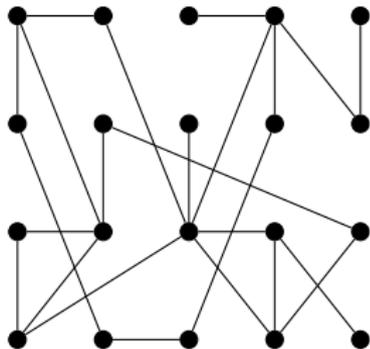
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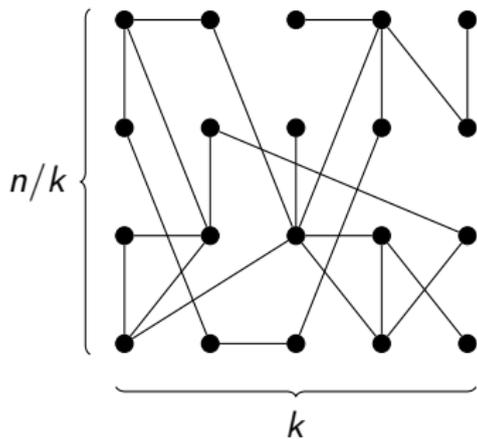
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- **Corollary:**  $\text{ETH} \Rightarrow \text{FPT} \neq \text{W}[1]$
- We start from an instance of **3-COLORING**, for which we already have a  $2^{\mathcal{O}(n)}$  lower bound.

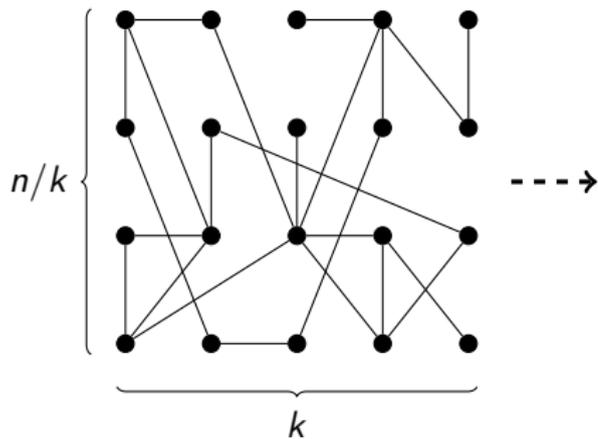
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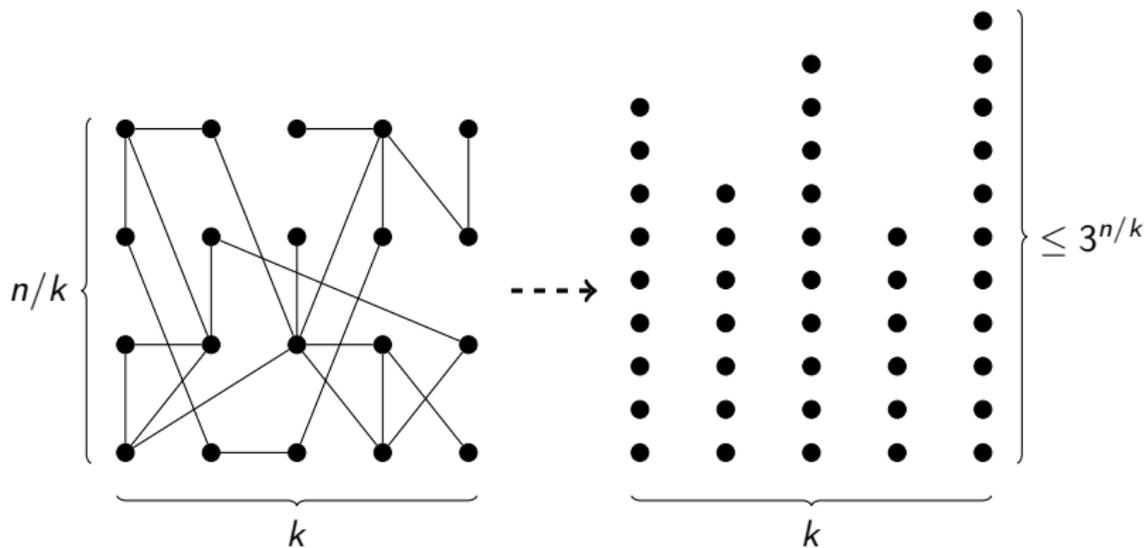


Partition vertices into  $k$  groups with  $n/k$  vertices each.

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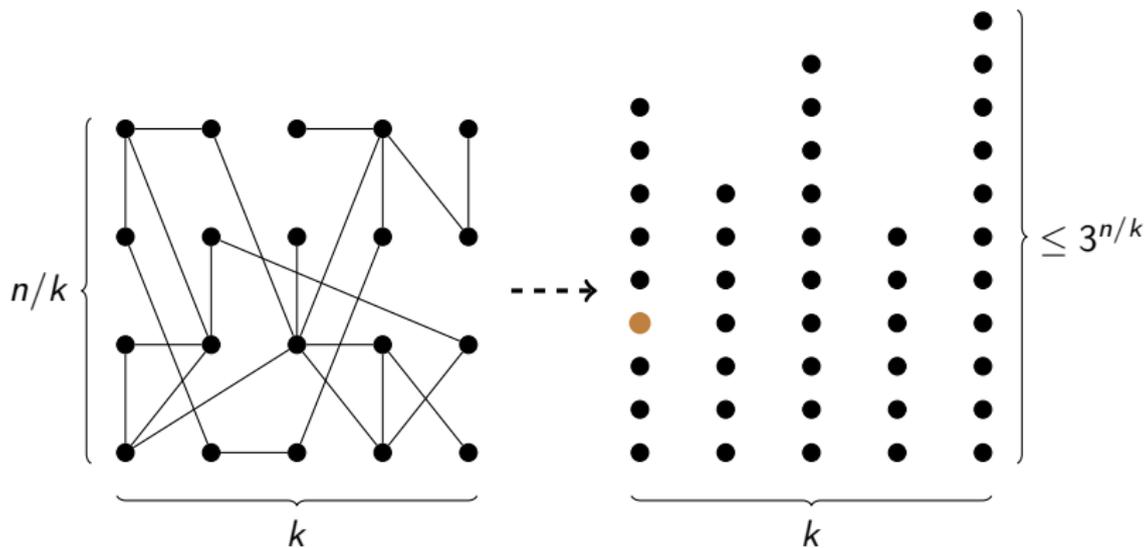


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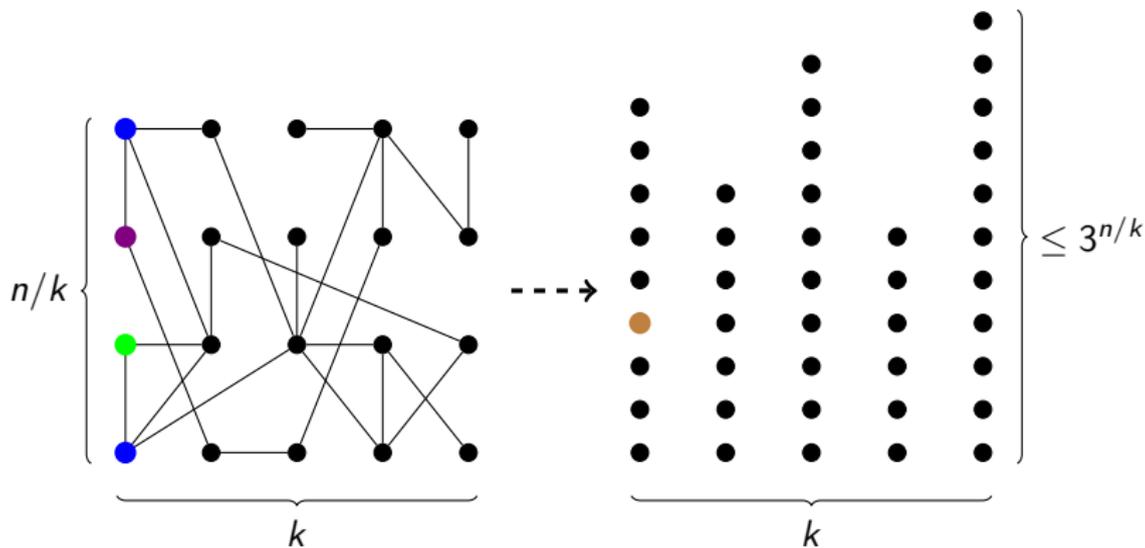
Create one vertex per each **consistent coloring** of each group.

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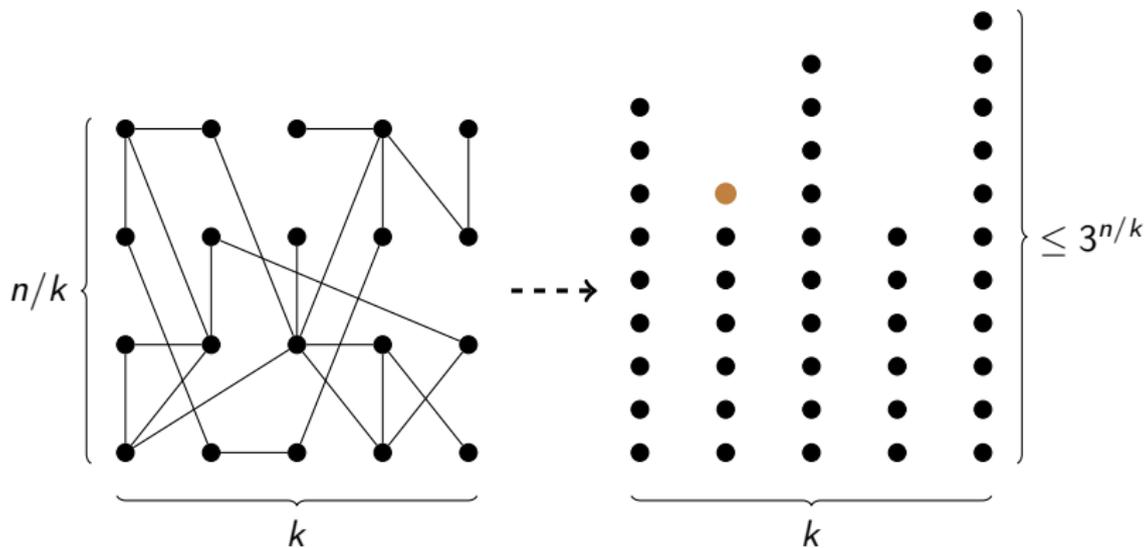
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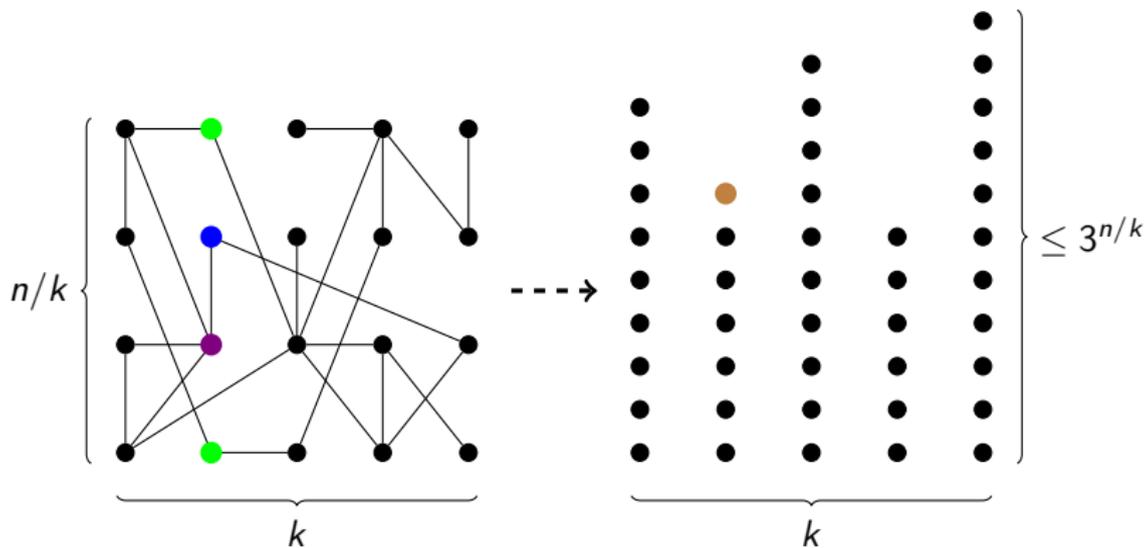
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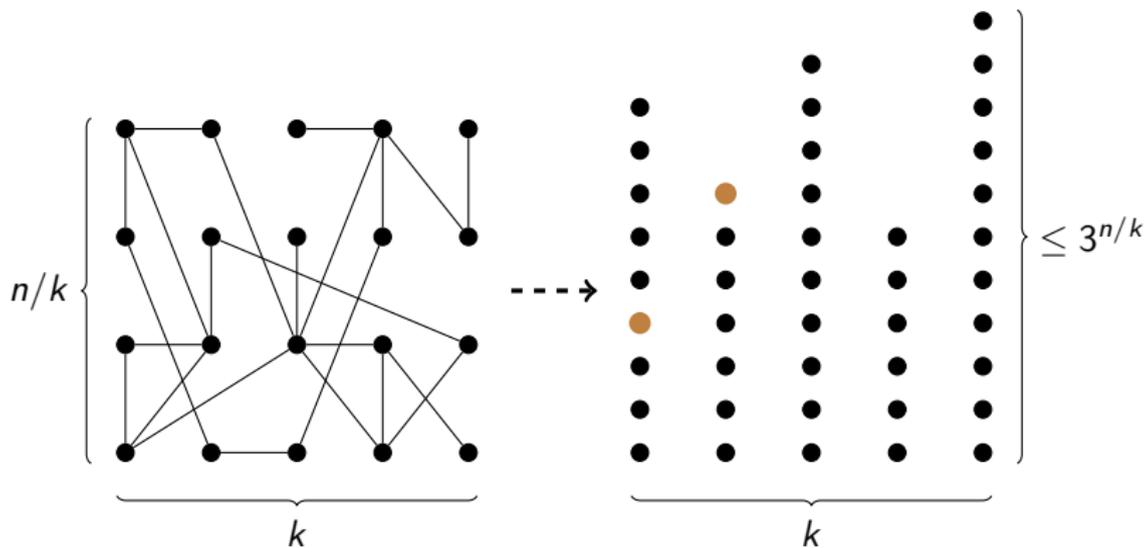
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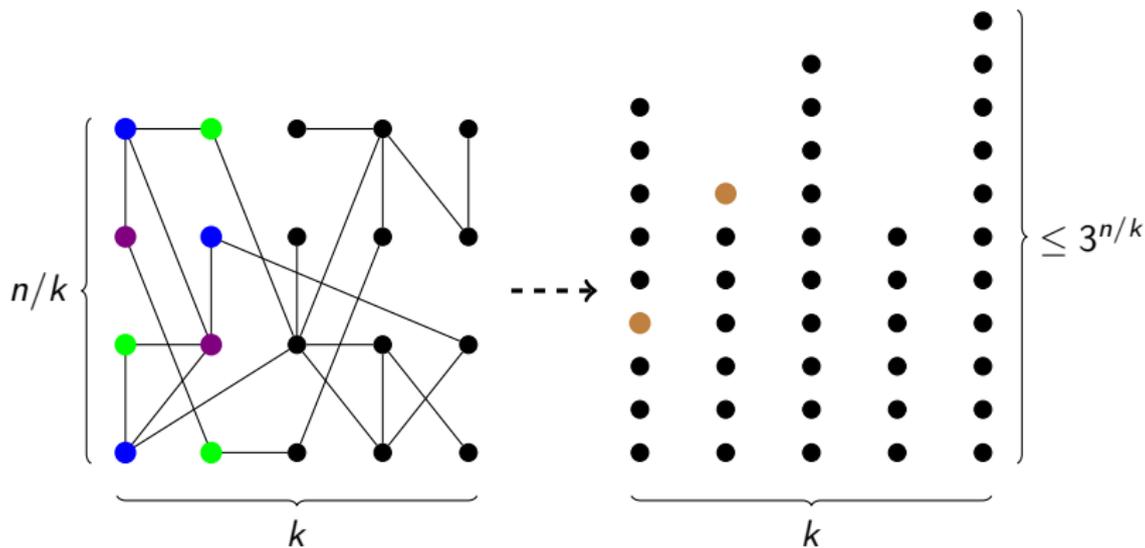
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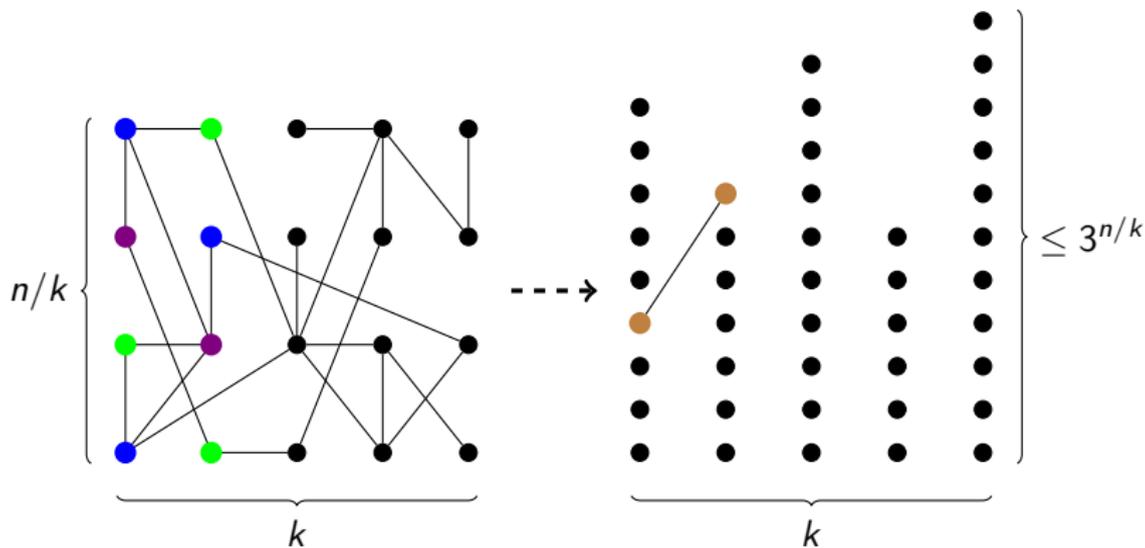
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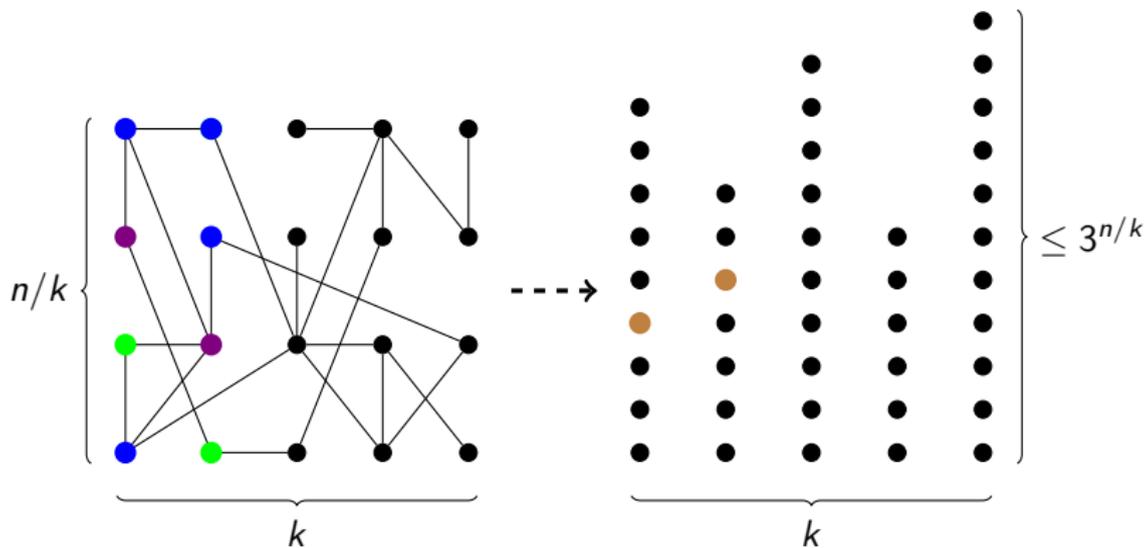
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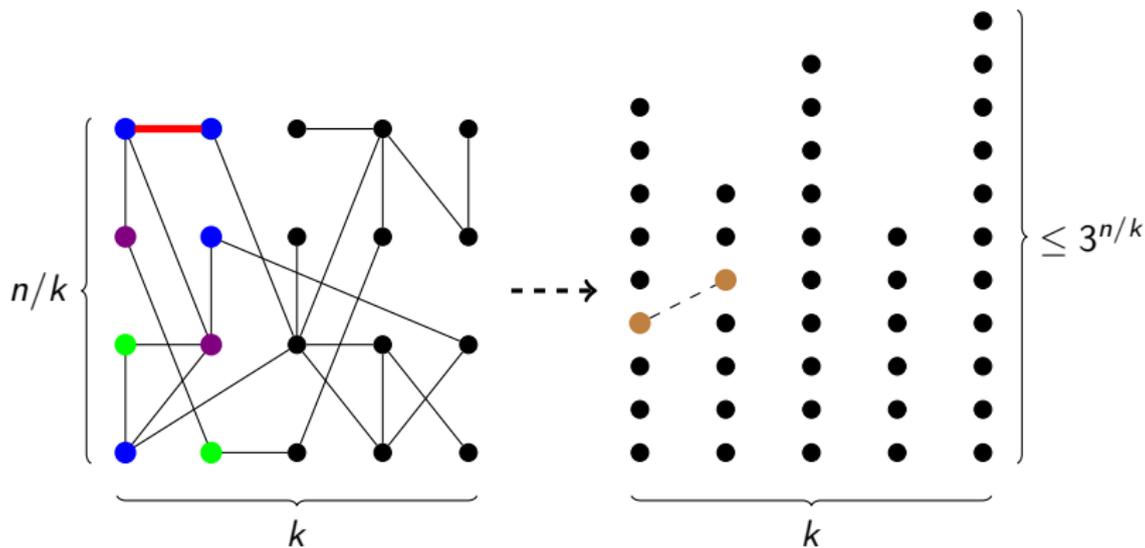
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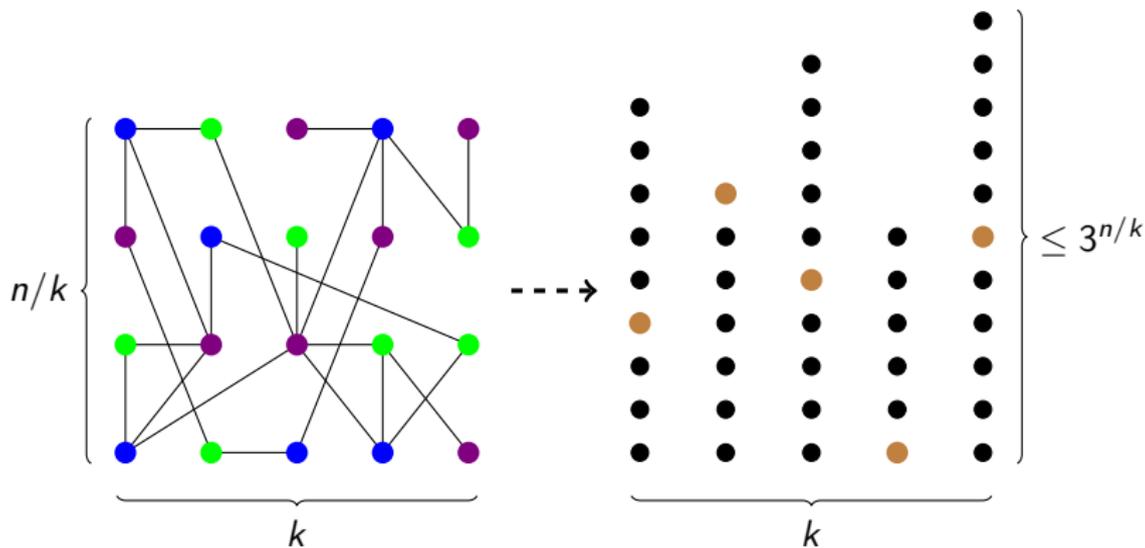
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A 3-coloring on the left corresponds to a  $k$ -clique on the right.

Left graph admits 3-coloring iff right graph contains  $k$ -clique.

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Unless ETH fails, CLIQUE cannot be solved in time  $f(k) \cdot n^{o(k)}$  for any computable function  $f$ .

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- **Intuition:** We embed the  $3^n$  solution space of 3-COLORING into the  $N^k$  solution space of CLIQUE.

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  - Quadratic blow-up  $\rightsquigarrow f(k') \cdot n^{o(\sqrt{k'})}$  lower bound

## PLANAR SCATTERED SET

**I:** An edge-weighted planar graph  $G$ ,  $d \in \mathbb{R}^+$ ,  $k \in \mathbb{N}$

**Q:** Are there are  $k$  vertices pairwise at distance  $\geq d$  from each other?

- There is an algorithm with running time  $n^{O(\sqrt{k})}$ .
- Under ETH, there is no algorithm with running time  $f(k) \cdot n^{o(\sqrt{k})}$ .
  - The reduction transforms an instance of CLIQUE with parameter  $k$  into an instance of PLANAR SCATTERED SET with parameter  $O(k^2)$ .

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## Lower bounds for parameterized problems under ETH

Suppose  $L$  admits a polynomial-time reduction from 3SAT with output parameter  $k \leq f(n + m)$ .

Then  $L$  does not admit an  $\mathcal{O}^*(2^{\mathcal{O}(f^{-1}(k))})$  time algorithm unless ETH fails.

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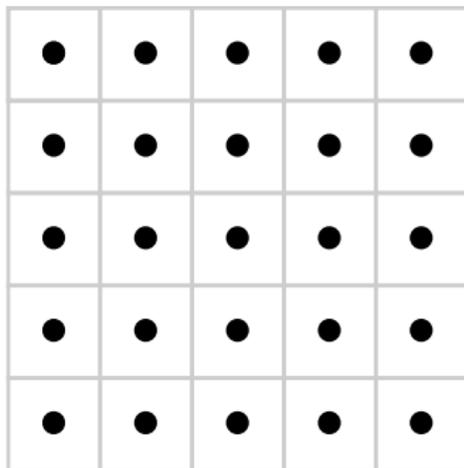
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- We focus on (b), since this is the most typical behavior in parameterized algorithms.

## $k \times k$ -CLIQUE

- I:** A graph  $H$  on vertex set  $\{1, \dots, k\} \times \{1, \dots, k\}$
- Q:** Is there a  $k$ -clique in  $H$  that contains exactly one vertex from each row?

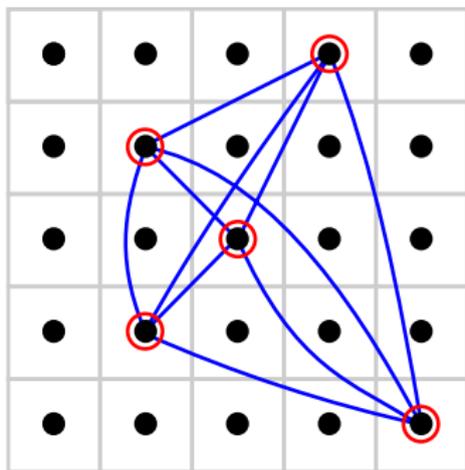
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## Corollary

Unless ETH fails, there is no algorithm for  $k \times k$ -CLIQUE with running time  $\mathcal{O}^*(2^{\mathcal{O}(k \log k)})$ .

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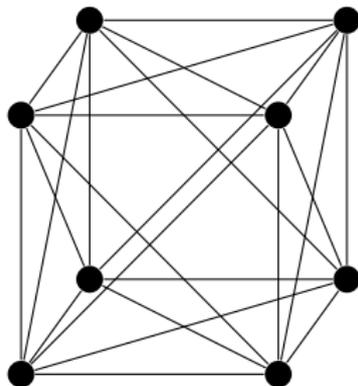
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- **Further:** treewidth dynamic programming, e.g. CYCLE PACKING,

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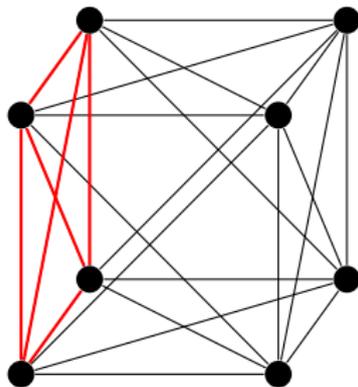


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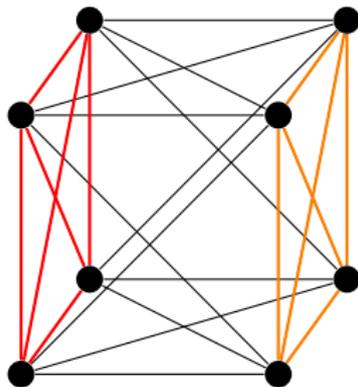


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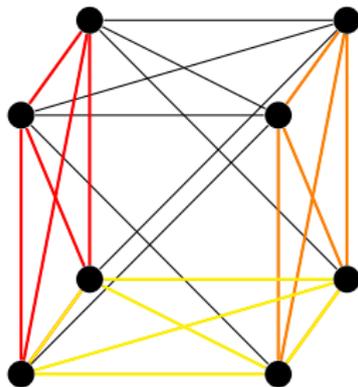


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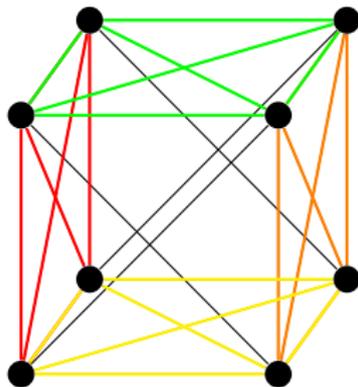


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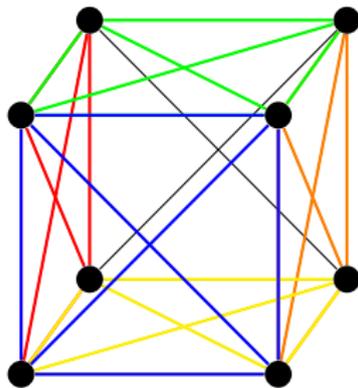


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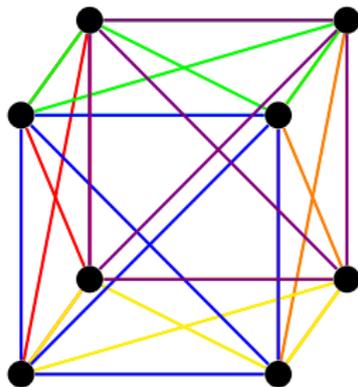
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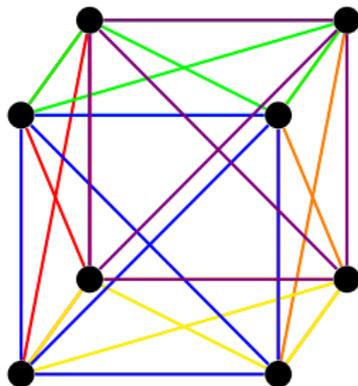


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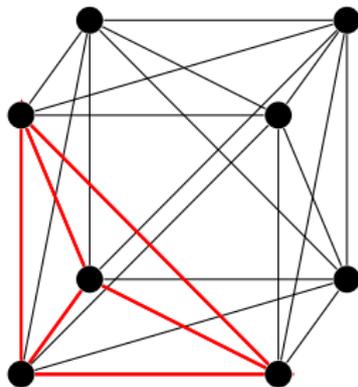
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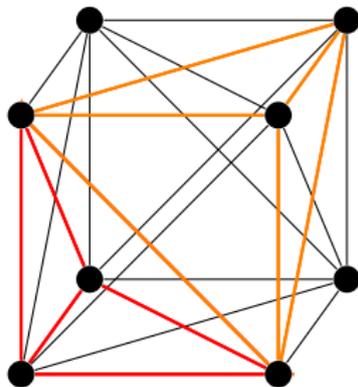


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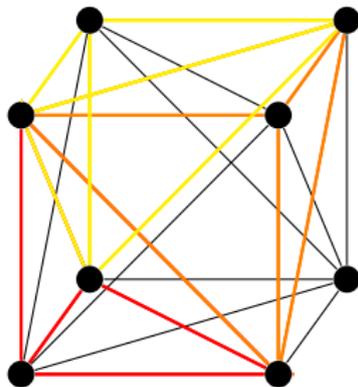


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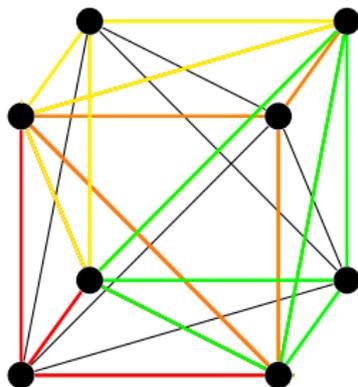


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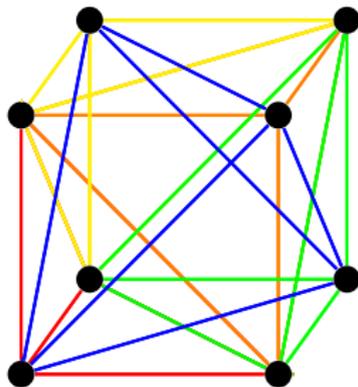


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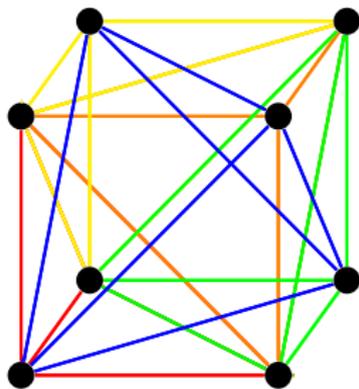


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- **Thank you for your attention!**